

## ASSP

# Dual Serial Input PLL Frequency Synthesizer

## MB15F07SL

### ■ DESCRIPTION

The Fujitsu MB15F07SL is a serial input Phase Locked Loop (PLL) frequency synthesizer with two 1100 MHz prescalers. The two 1100 MHz prescalers have a dual modulus division ratio of 128/129 or 64/65 enabling pulse swallowing operation.

The supply voltage range is between 2.4 V and 3.6 V. The MB15F07SL uses the latest BiCMOS process. As a result, the supply current is typically 5 mA at 2.7 V. A refined charge pump supplies a well-balanced output current of 1.5 mA or 6 mA. The charge pump current is selectable by serial data.

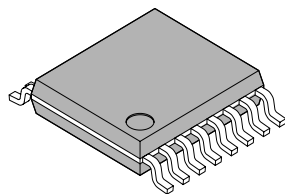
MB15F07SL is ideally suited for wireless mobile communications, such as GSM and PDC.

### ■ FEATURES

- High frequency operation: PLL 1, 2: 1100 MHz max
- Low power supply voltage:  $V_{CC} = 2.4$  to 3.6 V
- Ultra Low power supply current:  $I_{CC} = 5.0$  mA typ. ( $V_{CC} = 2.7$  V,  $T_a = +25^\circ\text{C}$ , in PLL1, 2 locking state)  
 $I_{CC} = 5.5$  mA typ. ( $V_{CC} = 3.0$  V,  $T_a = +25^\circ\text{C}$ , in PLL1, 2 locking state)
- Direct power saving function: Power supply current in power saving mode  
Typ. 0.1  $\mu\text{A}$  ( $V_{CC} = 3.0$  V,  $T_a = +25^\circ\text{C}$ ), Max. 10  $\mu\text{A}$  ( $V_{CC} = 3.0$  V)
- Dual modulus prescaler: 1100 MHz prescaler (64/65, 128/129)
- Serial input 14-bit programmable reference divider: R = 3 to 16,383
- Serial input programmable divider consisting of:
  - Binary 7-bit swallow counter: 0 to 127
  - Binary 11-bit programmable counter: 3 to 2,047
- Software selectable charge pump current
- On-chip phase control for phase comparator
- Operating temperature:  $T_a = -40$  to  $+85^\circ\text{C}$

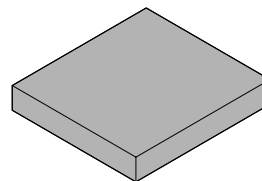
### ■ PACKAGES

16-pin plastic SSOP



(FPT-16P-M05)

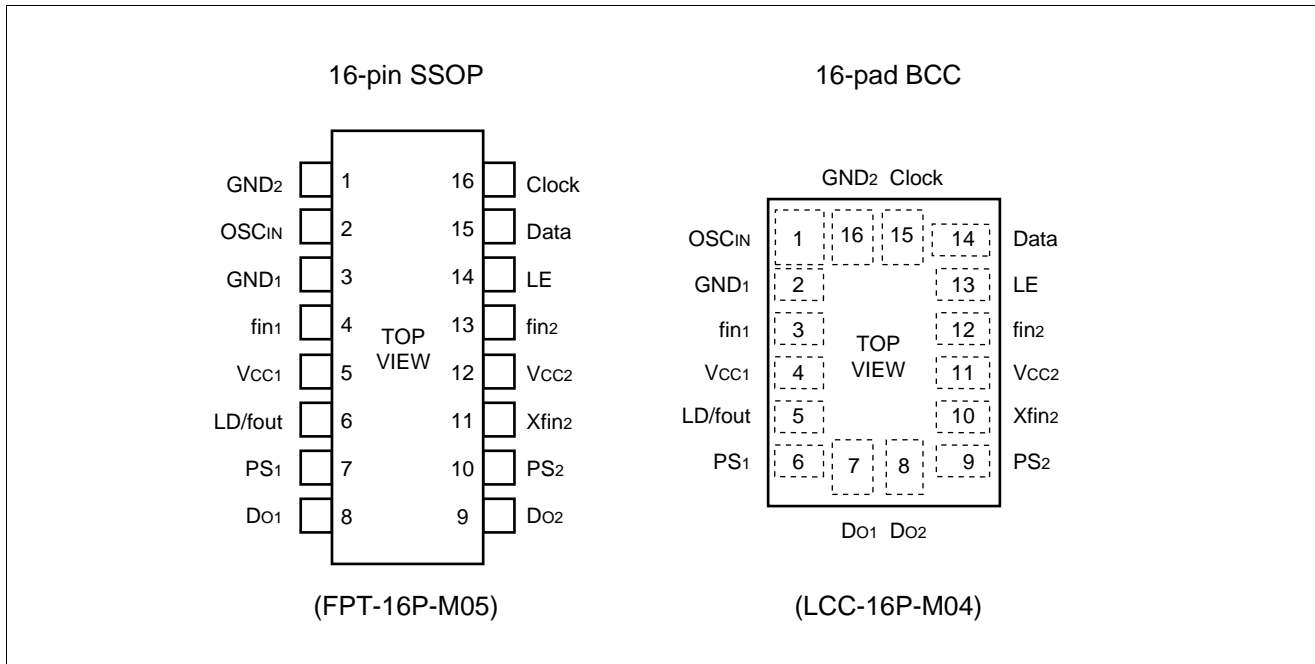
16-pad plastic BCC



(LCC-16P-M04)

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## ■ PIN ASSIGNMENTS

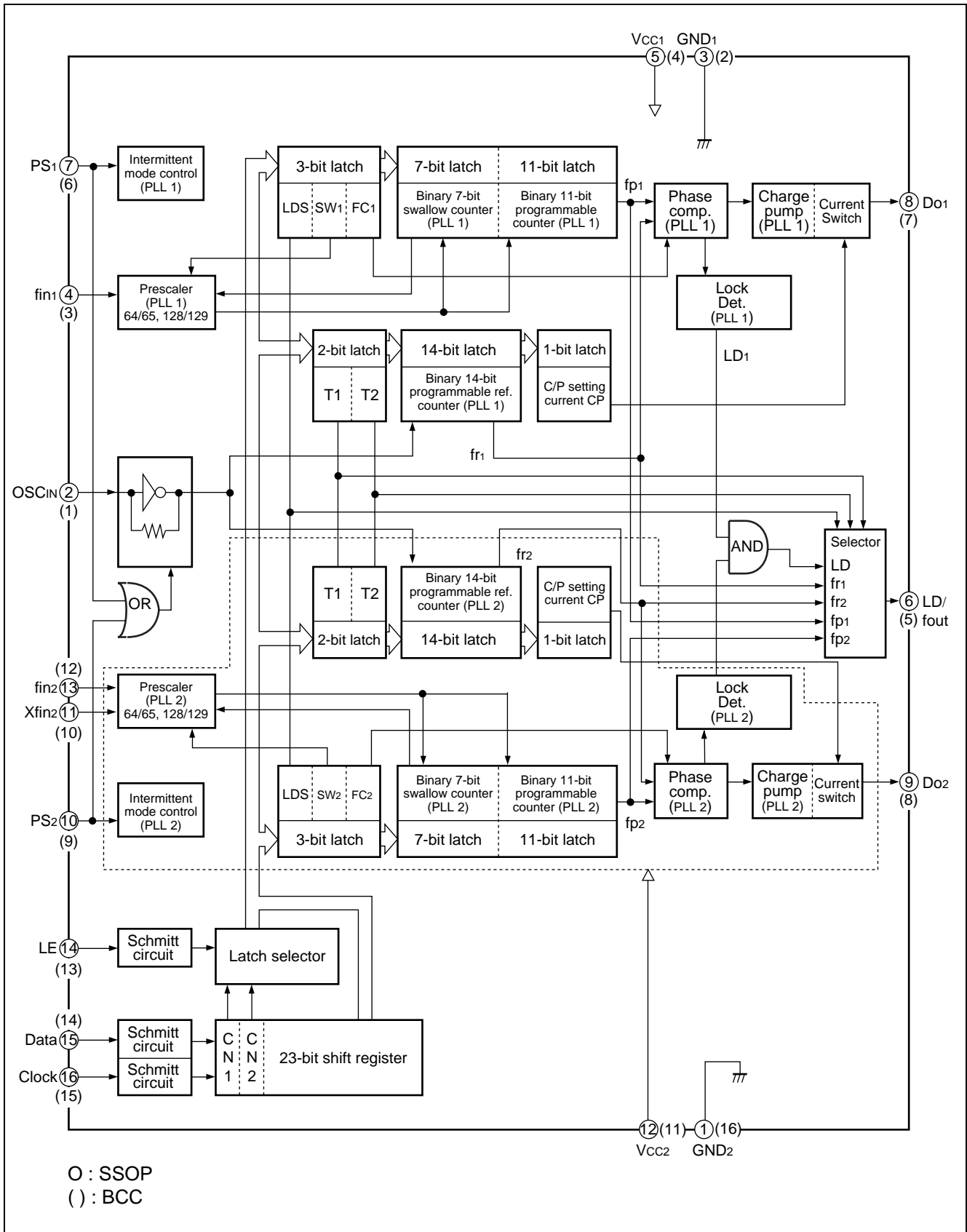


## ■ PIN DESCRIPTIONS

Pin no.		Pin name	I/O	Descriptions
SSOP-16	BCC-16			
1	16	GND <sub>2</sub>	–	Ground for PLL 2 section.
2	1	OSC <sub>IN</sub>	I	The programmable reference divider input. TCXO should be connected with a AC coupling capacitor.
3	2	GND <sub>1</sub>	–	Ground for the PLL 1 section.
4	3	fin <sub>1</sub>	I	Prescaler input pin for the PLL 1. Connection to an external VCO should be via AC coupling.
5	4	V <sub>CC1</sub>	–	Power supply voltage input pin for the PLL 1 section.
6	5	LD/fout	O	Lock detect signal output (LD)/phase comparator monitoring output (fout). The output signal is selected by LDS bit in a serial data. LDS bit = "H" ; outputs fout signal LDS bit = "L" ; outputs LD signal
7	6	PS <sub>1</sub>	I	Power saving mode control for the PLL 1 section. This pin must be set at "L" during Power-ON. (Open is prohibited.) PS <sub>1</sub> = "H" ; Normal mode PS <sub>1</sub> = "L" ; Power saving mode
8	7	Do <sub>1</sub>	O	Charge pump output for the PLL 1 section. Phase characteristics of the phase detector can be selected via programming of the FC-bit.
9	8	Do <sub>2</sub>	O	Charge pump output for the PLL 2 section. Phase characteristics of the phase detector can be selected via programming of the FC-bit.
10	9	PS <sub>2</sub>	I	Power saving mode control for the PLL 2 section. This pin must be set at "L" during Power-ON. (Open is prohibited.) PS <sub>2</sub> = "H" ; Normal mode PS <sub>2</sub> = "L" ; Power saving mode
11	10	Xfin <sub>2</sub>	I	Prescaler complementary input for the PLL 2 section. This pin should be grounded via a capacitor.
12	11	V <sub>CC2</sub>	–	Power supply voltage input pin for the PLL 2 section, the shift register and the oscillator input buffer. When power is OFF, latched data of PLL 2 is lost.
13	12	fin <sub>2</sub>	I	Prescaler input pin for the PLL 2. Connection to an external VCO should be via AC coupling.
14	13	LE	I	Load enable signal input (with a schmitt trigger input buffer.) When the LE bit is set "H", data in the shift register is transferred to the corresponding latch according to the control bit in the serial data.
15	14	Data	I	Serial data input (with a schmitt trigger input buffer.) Data is transferred to the corresponding latch (PLL 1-ref. counter, PLL 1-prog. counter, PLL 2-ref. counter, PLL 2-prog. counter) according to the control bit in the serial data.
16	15	Clock	I	Clock input for the 23-bit shift register (with a schmitt trigger input buffer.) One bit of data is shifted into the shift register on a rising edge of the clock.

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## ■ BLOCK DIAGRAM



## ■ ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Rating		Unit	Remark
		Min.	Max.		
Power supply voltage	$V_{CC}$	-0.5	+4.0	V	
Input voltage	$V_I$	-0.5	$V_{CC} + 0.5$	V	
Output voltage	$V_O$	GND	$V_{CC}$	V	
Storage temperature	$T_{stg}$	-55	+125	°C	

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

## ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Value			Unit	Remark
		Min.	Typ.	Max.		
Power supply voltage	$V_{CC}$	2.4	3.0	3.6	V	
Input voltage	$V_I$	GND	-	$V_{CC}$	V	
Operating temperature	$T_a$	-40	-	+85	°C	

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

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## ■ ELECTRICAL CHARACTERISTICS

( $V_{CC} = 2.4\text{ V to }3.6\text{ V}$ ,  $T_a = -40\text{ to }+85^\circ\text{C}$ )

Parameter	Symbol	Condition	Value			Unit	
			Min.	Typ.	Max.		
Power supply current*1	$I_{CC}^{*1}$	PLL 1, PLL 2 total, $fin_1 = fin_2 = 1100\text{ MHz}$ , $V_{CC1} = V_{CC2} = 2.7\text{ V}$ ( $V_{CC1} = V_{CC2} = 3.0\text{ V}$ )	–	5.0 (5.5)	–	mA	
Power saving current	$I_{PS}$	$PS_1 = PS_2 = \text{“L”}$	–	$0.1^{*2}$	10	$\mu\text{A}$	
Operating frequency	$fin_1^{*3}$	$fin_1$	PLL 1	100	–	1100	MHz
	$fin_2^{*3}$	$fin_2$	PLL 2	100	–	1100	MHz
	OSC <sub>IN</sub>	fosc	–	3	–	40	MHz
Input sensitivity	$fin_1$	P $fin_1$	PLL 1, 50 $\Omega$ system	$-15^{*8}$	–	+2	dBm
	$fin_2$	P $fin_2$	PLL 2, 50 $\Omega$ system	$-15^{*8}$	–	+2	dBm
	OSC <sub>IN</sub>	V <sub>OSC</sub>	–	0.5	–	$V_{CC}$	Vp-p
“H” level input voltage	Data, Clock, LE	$V_{IH}$	Schmitt trigger input	$V_{CC} \times 0.7$ + 0.4	–	–	V
“L” level input voltage		$V_{IL}$	Schmitt trigger input	–	–	$V_{CC} \times 0.3$ – 0.4	
“H” level input voltage	$PS_1$ , $PS_2$	$V_{IH}$	–	$V_{CC} \times 0.7$	–	–	V
“L” level input voltage		$V_{IL}$	–	–	–	$V_{CC} \times 0.3$	
“H” level input current	Data, Clock, LE, $PS_1$ , $PS_2$	$I_{IH}^{*4}$	–	–1.0	–	+1.0	$\mu\text{A}$
“L” level input current		$I_{IL}^{*4}$	–	–1.0	–	+1.0	
“H” level input current	OSC <sub>IN</sub>	$I_{IH}$	–	0	–	+100	$\mu\text{A}$
“L” level input current		$I_{IL}^{*4}$	–	–100	–	0	
“H” level output voltage	LD/fout	$V_{OH}$	$V_{CC} = 3.0\text{ V}$ , $I_{OH} = -1\text{ mA}$	$V_{CC} - 0.4$	–	–	V
“L” level output voltage		$V_{OL}$	$V_{CC} = 3.0\text{ V}$ , $I_{OL} = 1\text{ mA}$	–	–	0.4	
“H” level output voltage	Do <sub>1</sub> Do <sub>2</sub>	$V_{DOH}$	$V_{CC} = 3.0\text{ V}$ , $I_{DOH} = -0.5\text{ mA}$	$V_{CC} - 0.4$	–	–	V
“L” level output voltage		$V_{DOL}$	$V_{CC} = 3.0\text{ V}$ , $I_{DOL} = 0.5\text{ mA}$	–	–	0.4	
High impedance cutoff current	Do <sub>1</sub> Do <sub>2</sub>	$I_{OFF}$	$V_{CC} = 3.0\text{ V}$ , $V_{OFF} = 0.5\text{ V to }V_{CC} - 0.5\text{ V}$	–	–	2.5	nA
“H” level output current	LD/fout	$I_{OH}^{*4}$	$V_{CC} = 3.0\text{ V}$	–	–	–1.0	mA
“L” level output current		$I_{OL}^{*4}$	$V_{CC} = 3.0\text{ V}$	1.0	–	–	

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(V<sub>CC</sub> = 2.4 to 3.6 V, Ta = -40 to +85°C)

Parameter	Symbol	Condition	Value			Unit	
			Min.	Typ.	Max.		
"H" level output current	Do1 Do2	I <sub>DOH</sub> *4	V <sub>CC</sub> = 3.0 V, V <sub>DOH</sub> = V <sub>CC</sub> /2, Ta = +25°C, CS bit = "H"	-	-6.0	-	mA
			V <sub>CC</sub> = 3.0 V, V <sub>DOH</sub> = V <sub>CC</sub> /2, Ta = +25°C, CS bit = "L"	-	-1.5	-	
"L" level output current	Do1 Do2	I <sub>DOL</sub>	V <sub>CC</sub> = 3.0 V, V <sub>DOL</sub> = V <sub>CC</sub> /2, Ta = +25°C, CS bit = "H"	-	6.0	-	
			V <sub>CC</sub> = 3.0 V, V <sub>DOL</sub> = V <sub>CC</sub> /2, Ta = +25°C, CS bit = "L"	-	1.5	-	
Charge pump current rate	I <sub>DOL</sub> /I <sub>DOH</sub>	I <sub>DOMT</sub> *5	V <sub>DO</sub> = V <sub>CC</sub> /2	-	3	-	%
	vs V <sub>DO</sub>	I <sub>DOVD</sub> *6	0.5 V ≤ V <sub>DO</sub> ≤ V <sub>CC</sub> - 0.5 V	-	10	-	%
	vs Ta	I <sub>DOTA</sub> *7	-40°C ≤ Ta ≤ +85°C, V <sub>DO</sub> = V <sub>CC</sub> /2	-	10	-	%

\*1: Conditions; fosc = 12 MHz, Ta = +25°C, in locking state.

\*2: V<sub>CC1</sub> = V<sub>CC2</sub> = 3.0 V, fosc = 12.8 MHz, Ta = +25°C, in power saving mode.

\*3: AC coupling. 1000pF capacitor is connected under the condition of min. operating frequency.

\*4: The symbol "-" (minus) means direction of current flow.

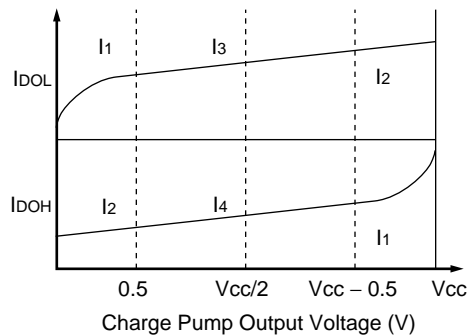
\*5: V<sub>CC</sub> = 3.0 V, Ta = +25°C (|I<sub>3</sub> - I<sub>4</sub>|)/[(|I<sub>3</sub> + I<sub>4</sub>)/2] × 100(%)

\*6: V<sub>CC</sub> = 3.0 V, Ta = +25°C [(|I<sub>2</sub> - I<sub>1</sub>|)/2]/[(|I<sub>1</sub> + I<sub>2</sub>)/2] × 100(%) (Applied to each I<sub>DOL</sub>, I<sub>DOH</sub>)

\*7: V<sub>CC</sub> = 3.0 V, [(|I<sub>DO(+85°C)</sub> - I<sub>DO(-40°C)</sub>|)/2]/[(|I<sub>DO(+85°C)</sub> + I<sub>DO(-40°C)</sub>|)/2] × 100(%) (Applied to each I<sub>DOL</sub>, I<sub>DOH</sub>)

\*8:

	Prescaler divided ratio	Charge pump current	Vfin1(min)
fin1	64/65	1.5 mA mode	-10 dBm
		6.0 mA mode	-10 dBm
	128/129	1.5 mA mode	-15 dBm
		6.0 mA mode	-15 dBm
fin2	64/65	1.5 mA mode	-15 dBm
		6.0 mA mode	-10 dBm
	128/129	1.5 mA mode	-15 dBm
		6.0 mA mode	-10 dBm
		1.5 mA mode	-15 dBm
		6.0 mA mode	-15 dBm



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## FUNCTIONAL DESCRIPTION

The divide ratio can be calculated using the following equation:

$$f_{VCO} = \{(M \times N) + A\} \times f_{osc} \div R \quad (A < N)$$

$f_{VCO}$  : Output frequency of external voltage controlled oscillator (VCO)

M : Preset divide ratio of dual modulus prescaler (64 or 128 for PLL 1/PLL 2)

N : Preset divide ratio of binary 11-bit programmable counter (3 to 2,047)

A : Preset divide ratio of binary 7-bit swallow counter ( $0 \leq A \leq 127$ )

$f_{osc}$  : Reference oscillation frequency

R : Preset divide ratio of binary 14-bit programmable reference counter (3 to 16,383)

## Serial Data Input

Serial data is entered using three pins, Data pin, Clock pin, and LE pin. Programmable dividers of PLL 1/PLL 2 sections, programmable reference dividers of PLL 1/PLL 2 sections are controlled individually.

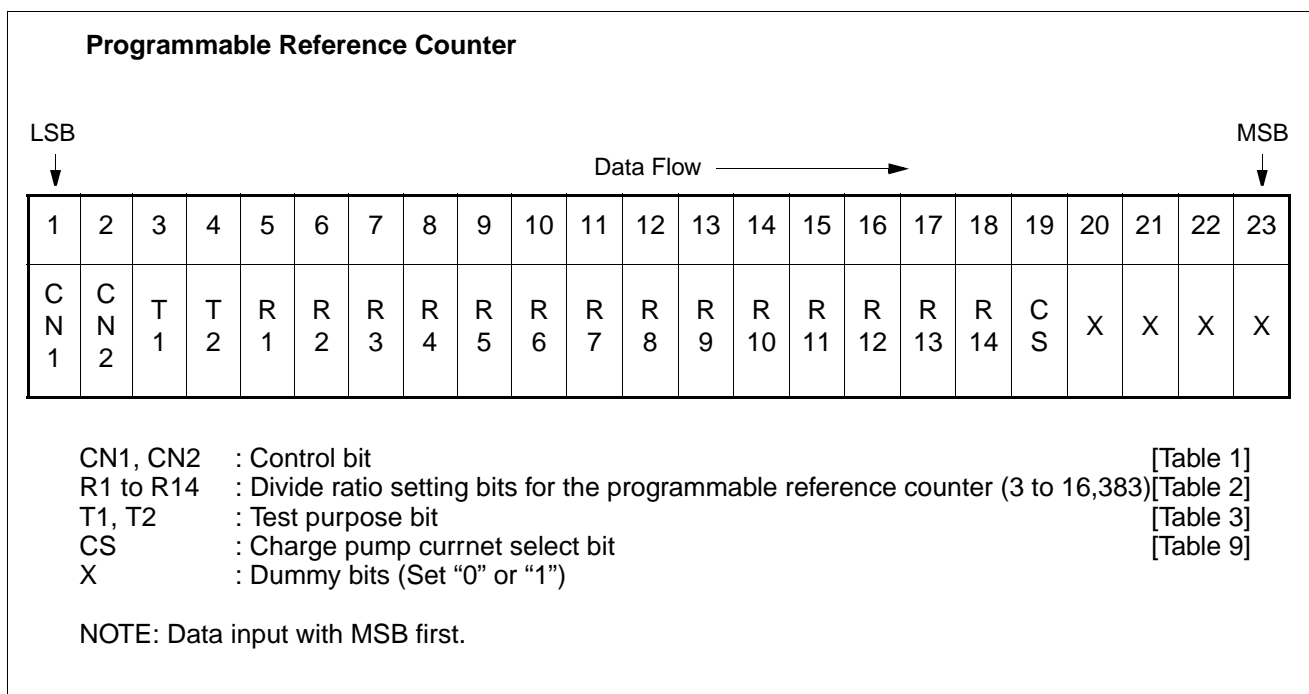
Serial data of binary data is entered through Data pin.

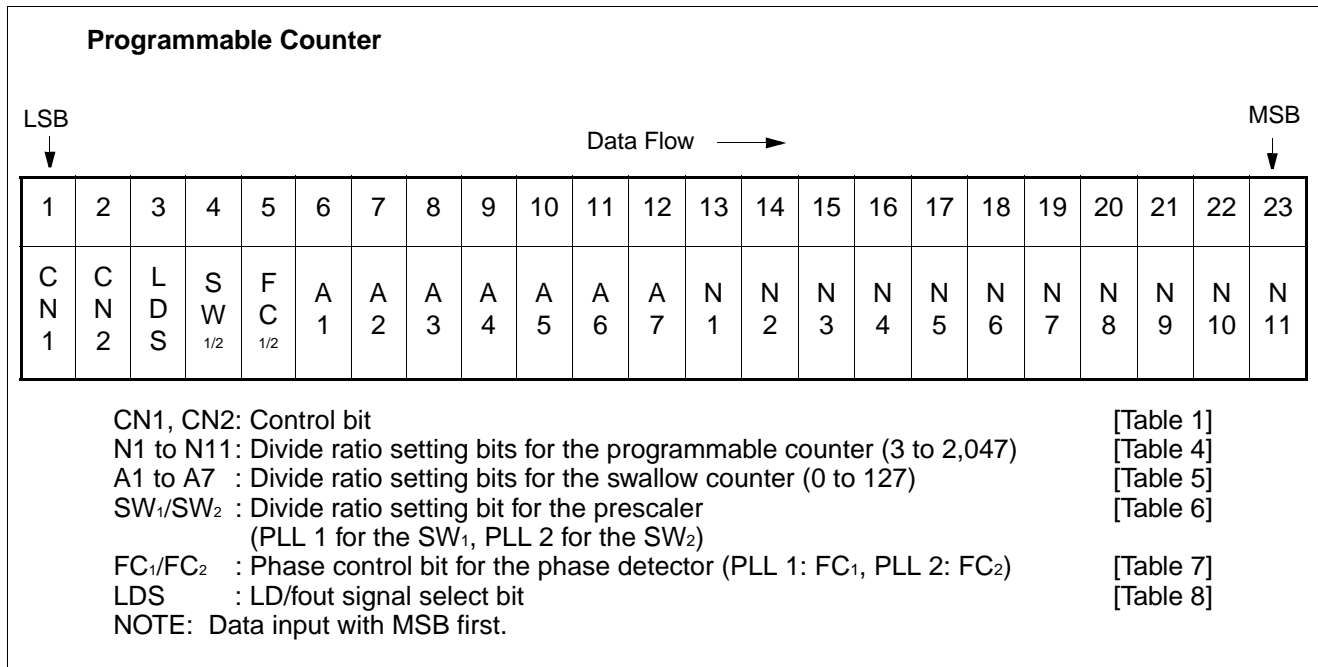
On rising edge of Clock, one bit of serial data is transferred into the shift register. When the LE signal is taken high, the data stored in the shift register is transferred to one of latch of them depending upon the control bit data setting.

**Table 1. Control Bit**

Control bit		Destination of serial data
CN1	CN2	
L	L	The programmable reference counter for the PLL 1
H	L	The programmable reference counter for the PLL 2
L	H	The programmable counter and the swallow counter for the PLL 1
H	H	The programmable counter and the swallow counter for the PLL 2

## Shift Register Configuration





**Table 2. Binary 14-bit Programmable Reference Counter Data Setting**

Divide ratio (R)	R14	R13	R12	R11	R10	R9	R8	R7	R6	R5	R4	R3	R2	R1
3	0	0	0	0	0	0	0	0	0	0	0	0	1	1
4	0	0	0	0	0	0	0	0	0	0	0	1	0	0
.	.	.	.	.	.	.	.	.	.	.	.	.	.	.
16383	1	1	1	1	1	1	1	1	1	1	1	1	1	1

Note: Divide ratio less than 3 is prohibited.

**Table 3. Test Purpose Bit Setting**

T1	T2	LD/fout pin state
L	L	Outputs fr <sub>1</sub> .
H	L	Outputs fr <sub>2</sub> .
L	H	Outputs fp <sub>1</sub> .
H	H	Outputs fp <sub>2</sub> .

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**Table 4. Binary 11-bit Programmable Counter Data Setting**

Divide ratio (N)	N11	N10	N9	N8	N7	N6	N5	N4	N3	N2	N1
3	0	0	0	0	0	0	0	0	0	1	1
4	0	0	0	0	0	0	0	0	1	0	0
·	·	·	·	·	·	·	·	·	·	·	·
2047	1	1	1	1	1	1	1	1	1	1	1

Note: Divide ratio less than 3 is prohibited.

**Table 5. Binary 7-bit Swallow Counter Data Setting**

Divide ratio (N)	A7	A6	A5	A4	A3	A2	A1
0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	1
·	·	·	·	·	·	·	·
127	1	1	1	1	1	1	1

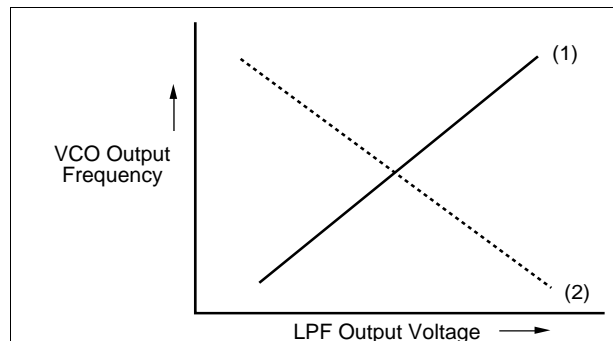
Note: Divide ratio (A) range = 0 to 127

**Table 6. Prescaler Data Setting**

		SW = "H"	SW = "L"
Prescaler divide ratio	PLL 1	64/65	128/129
	PLL 2	64/65	128/129

**Table 7. Phase Comparator Phase Switching Data Setting**

	FC <sub>1</sub> , FC <sub>2</sub> = "H"	FC <sub>1</sub> , FC <sub>2</sub> = "L"
	Do <sub>1</sub> , Do <sub>2</sub>	
fr > fp	H	L
fr = fp	Z	Z
fr < fp	L	H
VCO polarity	(1)	(2)



Note: • Z = High-impedance  
 • Depending upon the VCO and LPF polarity, FC bit should be set.

**Table 8. LD/fout Output Select Data Setting**

LDS	LD/fout output signal
H	fout (fr <sub>1</sub> /fr <sub>2</sub> , fp <sub>1</sub> /fp <sub>2</sub> ) signals
L	LD signal

**Table 9. Charge Pump Current Setting**

CS	Current value
H	±6.0 mA
L	±1.5 mA

### Power Saving Mode (Intermittent Mode Control Circuit)

**Table 10. PS Pin Setting**

PS pin	Status
H	Normal mode
L	Power saving mode

The intermittent mode control circuit reduces the PLL power consumption.

By setting the PS pin low, the device enters into the power saving mode, reducing the current consumption. See the Electrical Characteristics chart for the specific value.

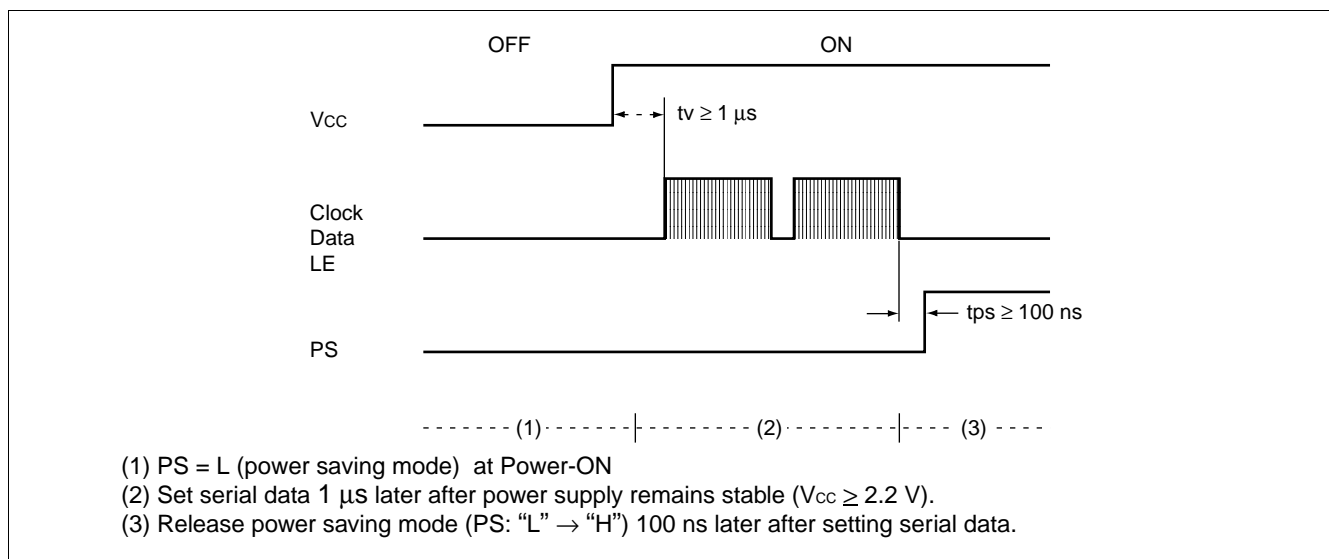
The phase detector output, Do, becomes high impedance.

For the dual PLL, the lock detector, LD, is as shown in the LD Output Logic table.

Setting the PS pin high, releases the power saving mode, and the device works normally.

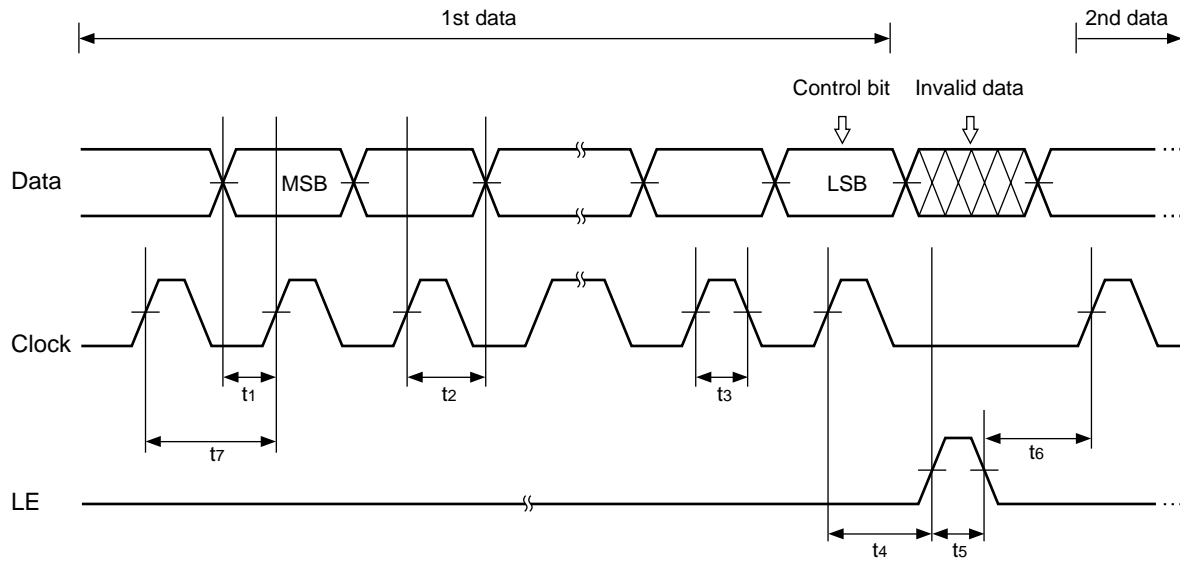
The intermittent mode control circuit also ensures a smooth startup when the device returns to normal operation. When the PLL is returned to normal operation, the phase comparator output signal is unpredictable. This is because of the unknown relationship between the comparison frequency (fp) and the reference frequency (fr) which can cause a major change in the comparator output, resulting in a VCO frequency jump and an increase in lockup time. To prevent a major VCO frequency jump, the intermittent mode control circuit limits the magnitude of the error signal from the phase detector when it returns to normal operation.

- Notes:
- When power (V<sub>CC</sub>) is first applied, the device must be in standby mode, PS = Low, for at least 1 μs.
  - PS pins must be set at “L” for Power-ON.



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## ■ SERIAL DATA INPUT TIMING



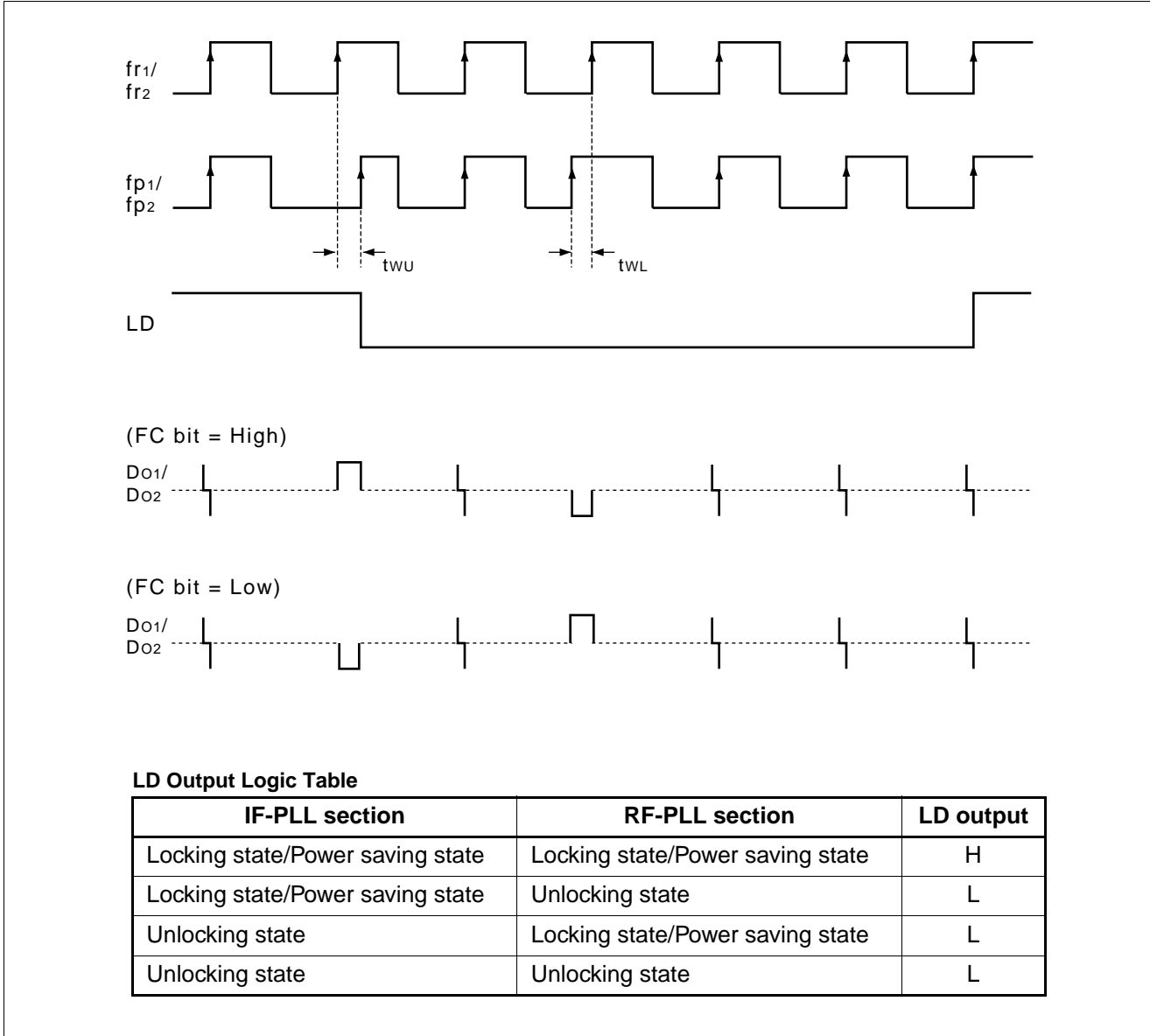
On rising edge of the clock, one bit of the data is transferred into the shift register.

Parameter	Min.	Typ.	Max.	Unit
$t_1$	20	–	–	ns
$t_2$	20	–	–	ns
$t_3$	30	–	–	ns
$t_4$	30	–	–	ns

Parameter	Min.	Typ.	Max.	Unit
$t_5$	100	–	–	ns
$t_6$	20	–	–	ns
$t_7$	100	–	–	ns

Note: LE should be “L” when the data is transferred into the shift register.

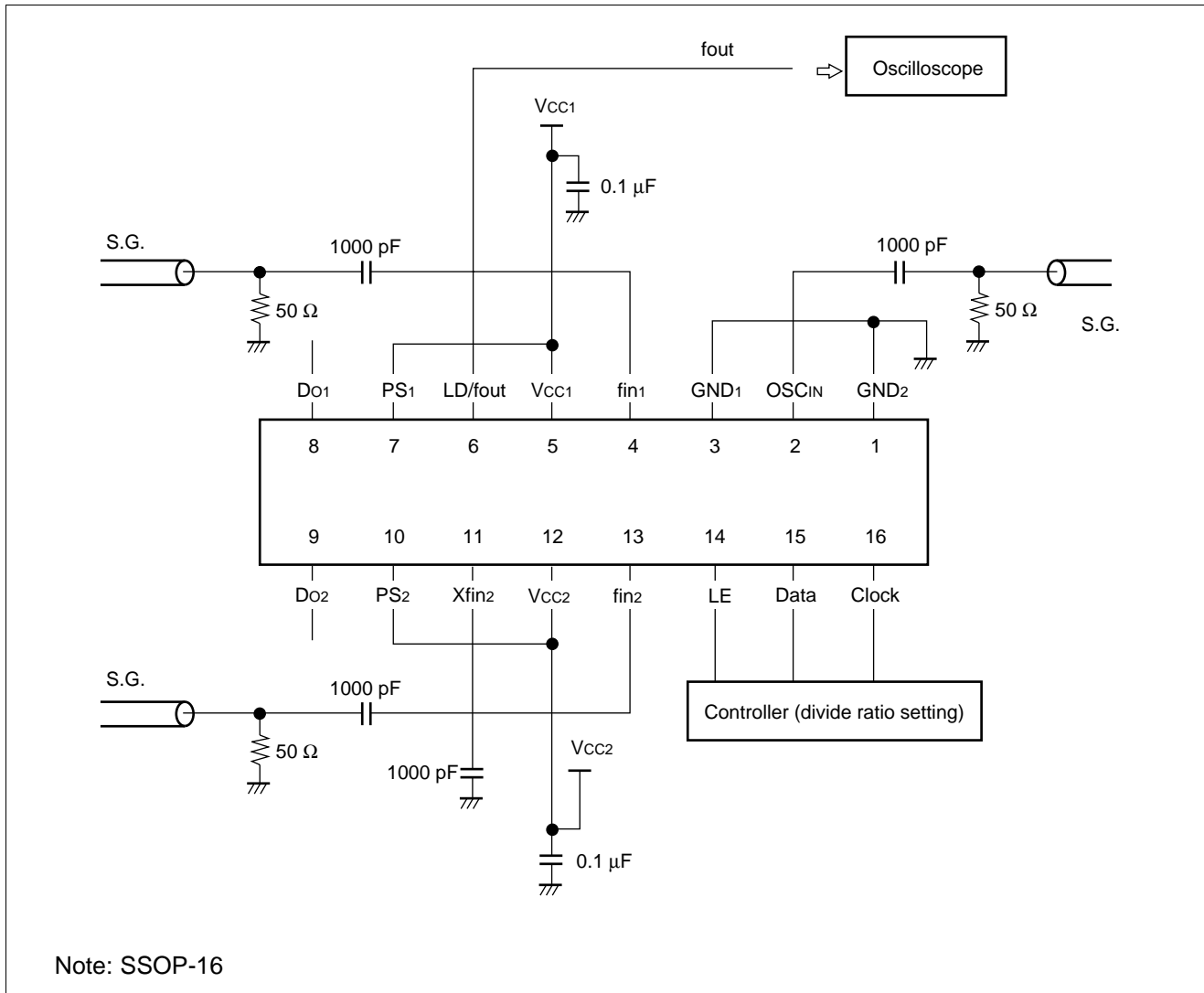
■ PHASE COMPARATOR OUTPUT WAVEFORM



- Notes:
- Phase error detection range =  $-2\pi$  to  $+2\pi$
  - Pulses on Do<sub>1/2</sub> signals are output to prevent dead zone.
  - LD output becomes low when phase error is  $t_{WU}$  or more.
  - LD output becomes high when phase error is  $t_{WL}$  or less and continues to be so for three cycles or more.
  - $t_{WU}$  and  $t_{WL}$  depend on OSC<sub>IN</sub> input frequency as follows.  
 $t_{WU} \geq 2/f_{osc}$ : i. e.  $t_{WU} \geq 156.3$  ns when  $f_{osc} = 12.8$  MHz  
 $t_{WL} \leq 4/f_{osc}$ : i. e.  $t_{WL} \leq 312.5$  ns when  $f_{osc} = 12.8$  MHz

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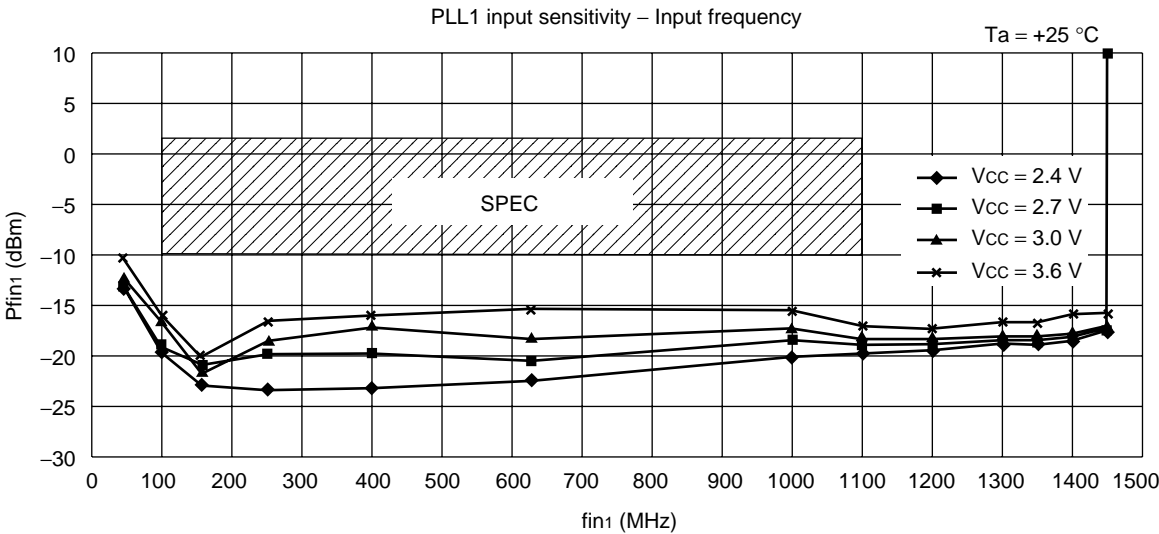
## MEASUREMENT CIRCUIT (for Measuring Input Sensitivity $f_{in}/OSC_{IN}$ )



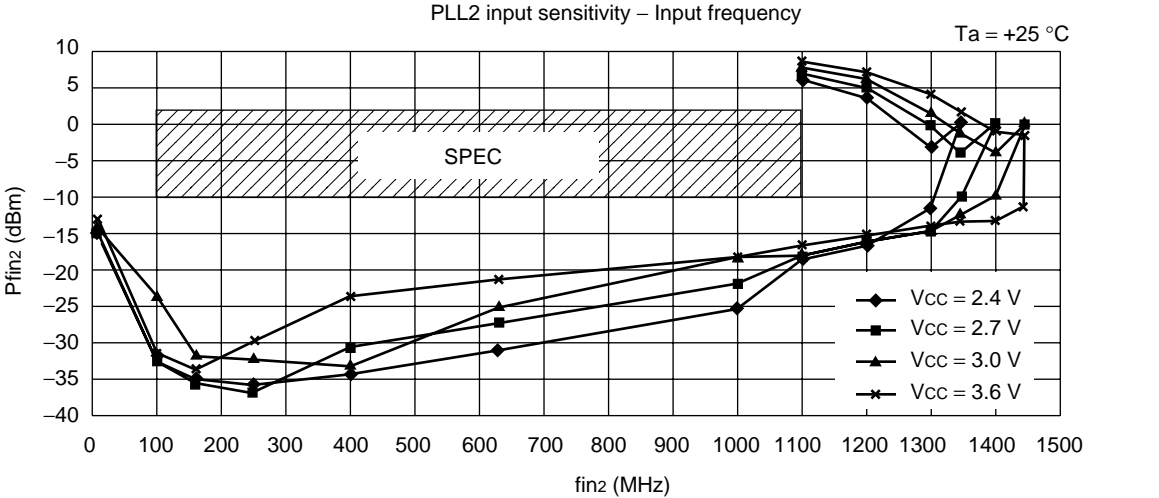
■ TYPICAL CHARACTERISTICS

1. fin input sensitivity

• fin1 input sensitivity

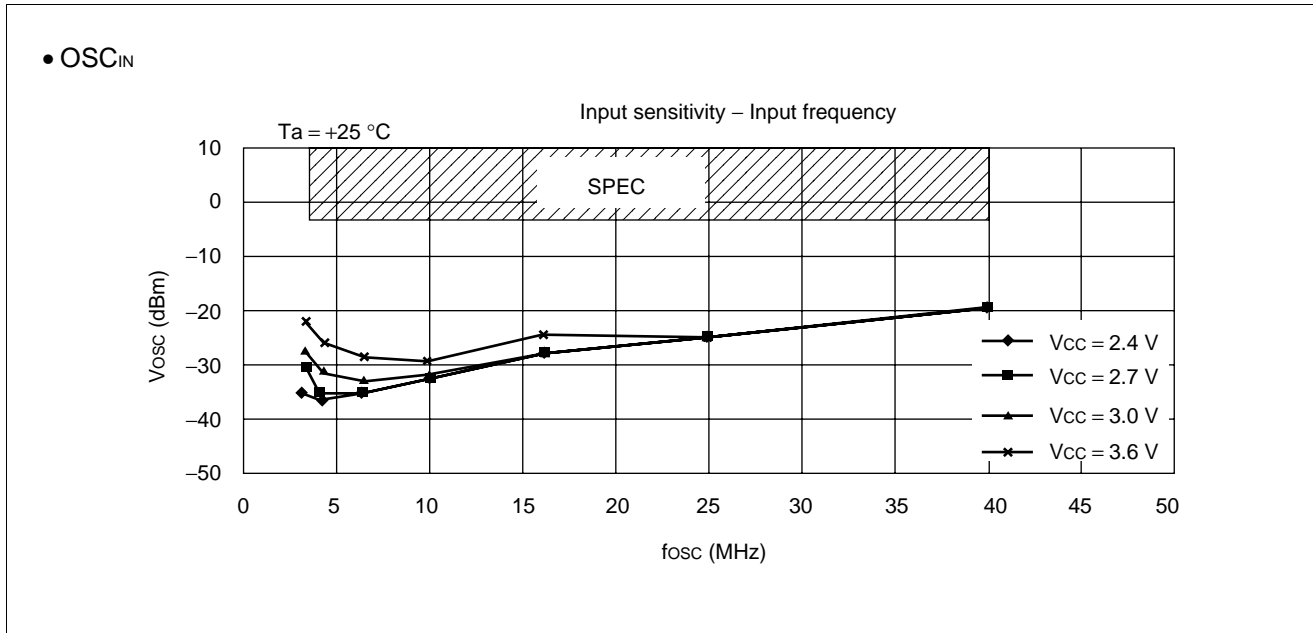


• fin2 input sensitivity



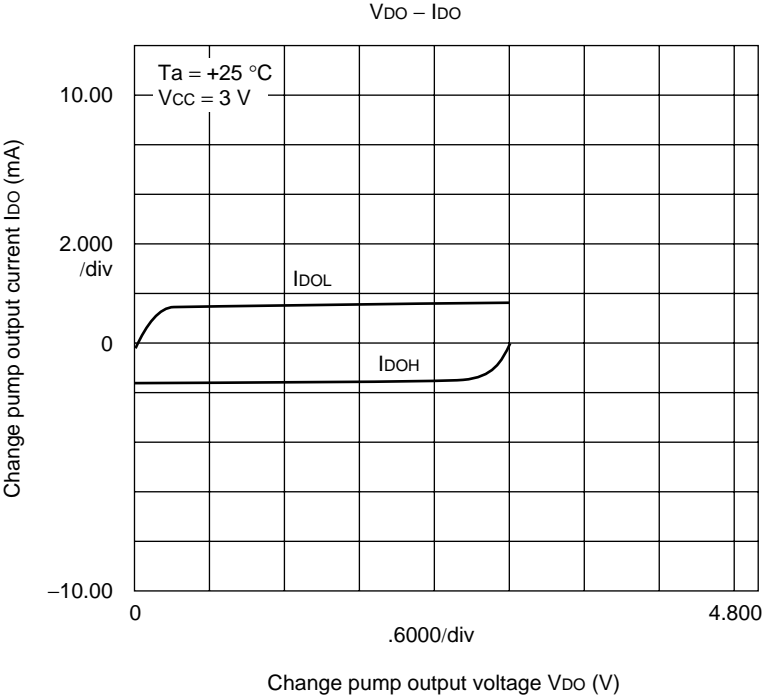
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## 2. OSC<sub>IN</sub> input sensitivity

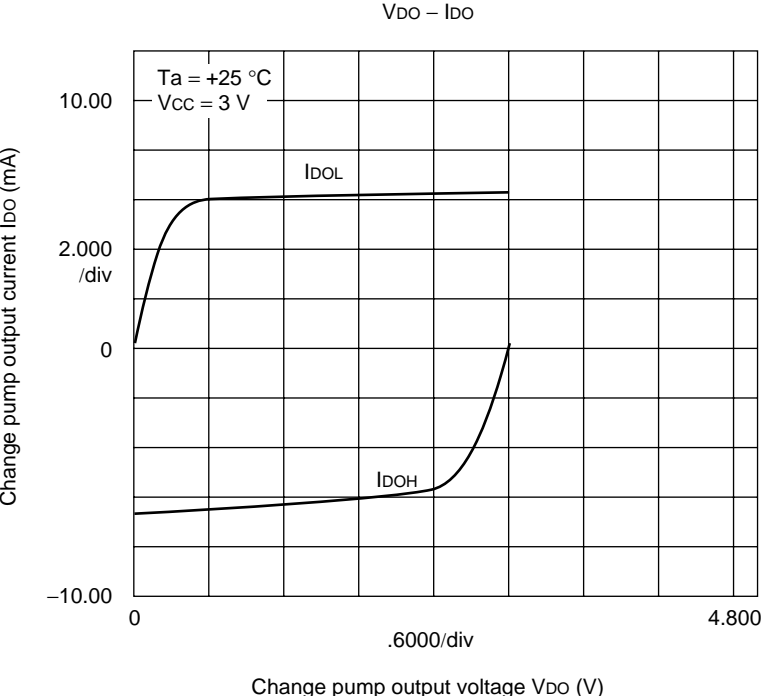


3. Do output current (PLL1)

- 1.5 mA mode



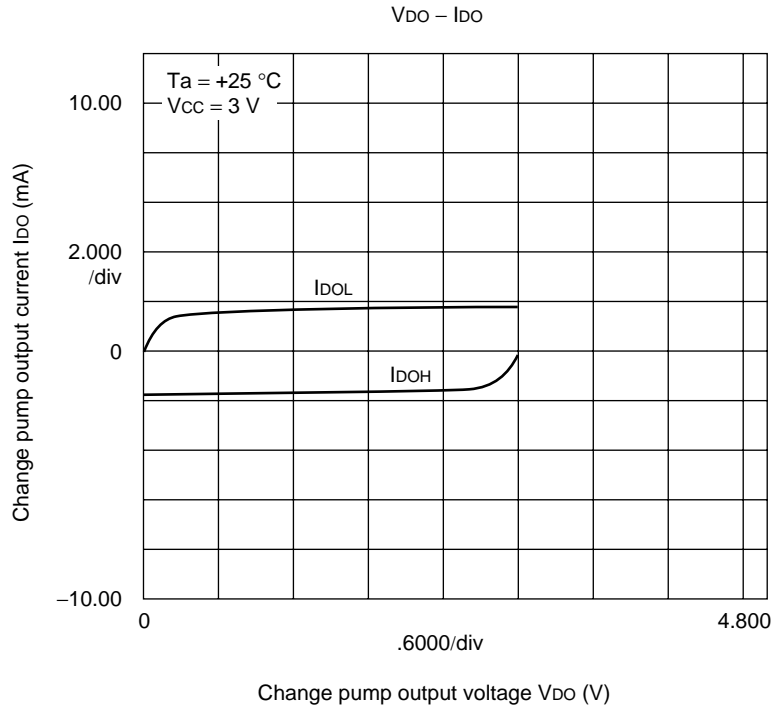
- 6.0 mA mode



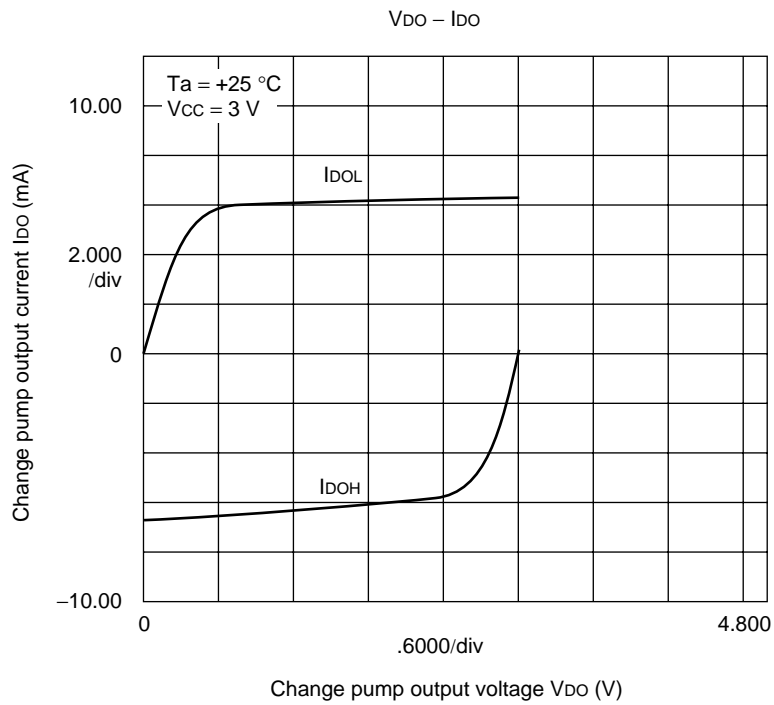
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## 4. Do output current (PLL2)

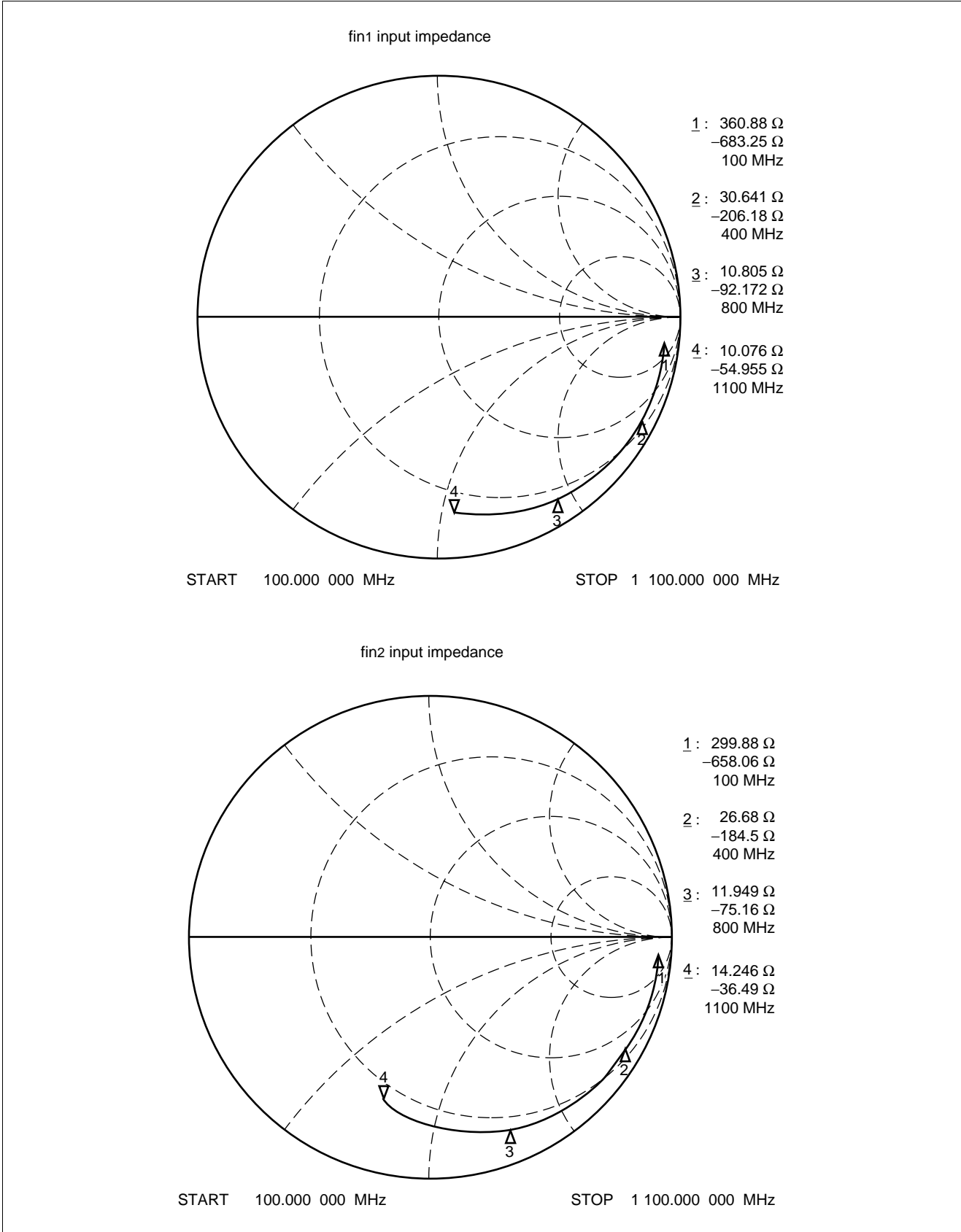
- 1.5 mA mode



- 6.0 mA mode

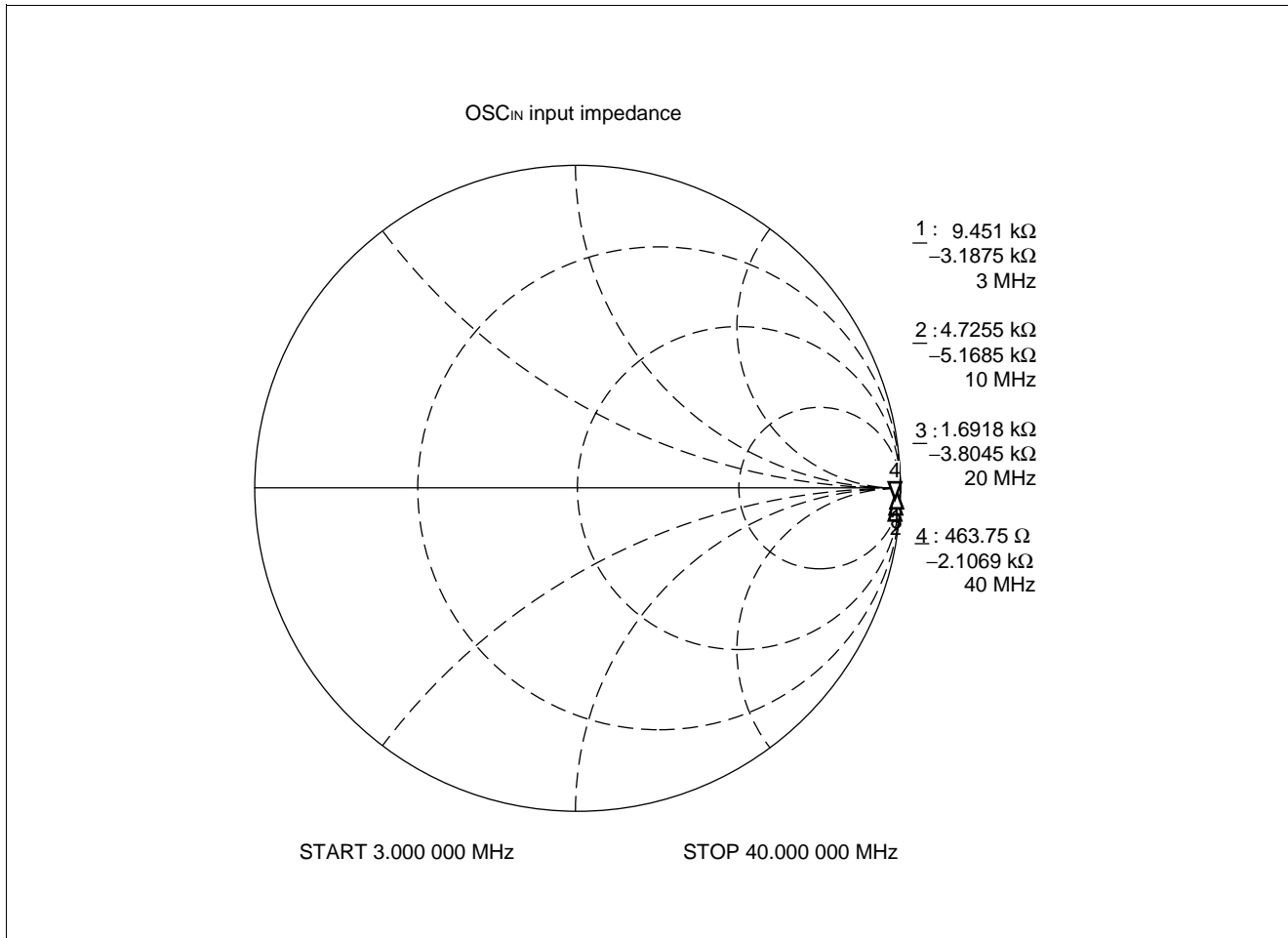


5. fin input impedance

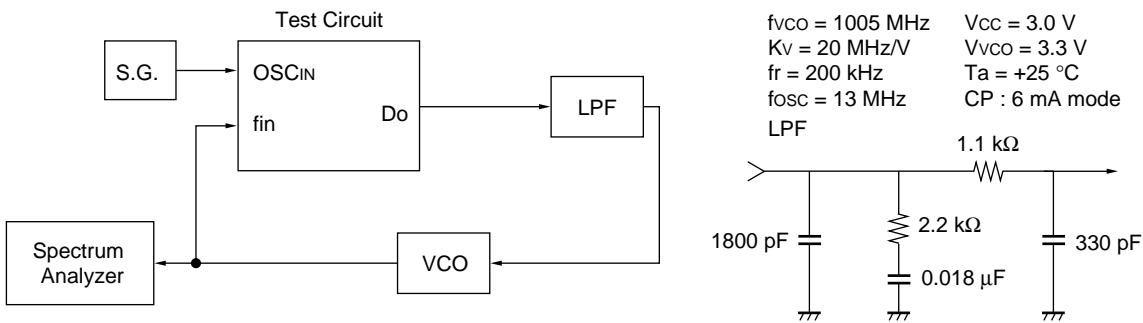


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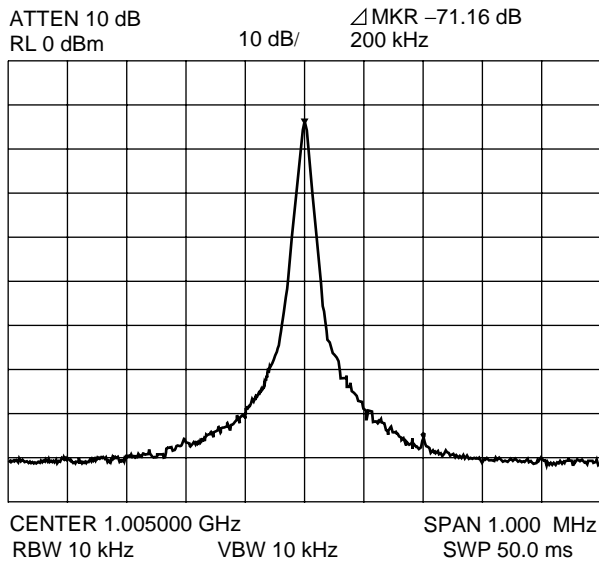
## 6. OSC<sub>IN</sub> input impedance



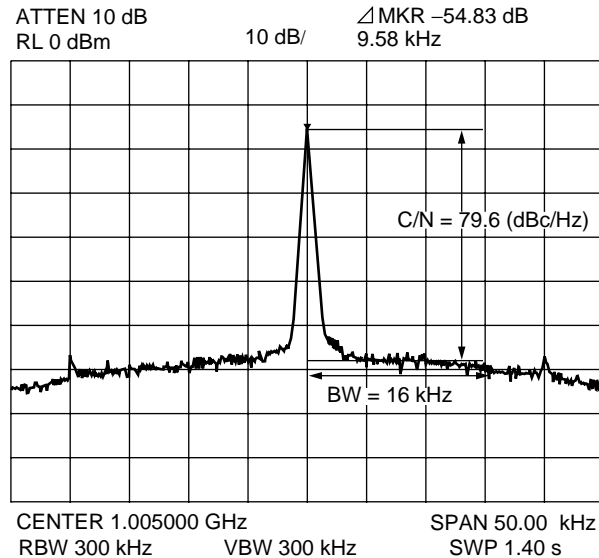
## REFERENCE INFORMATION



### • PLL Reference Leakage



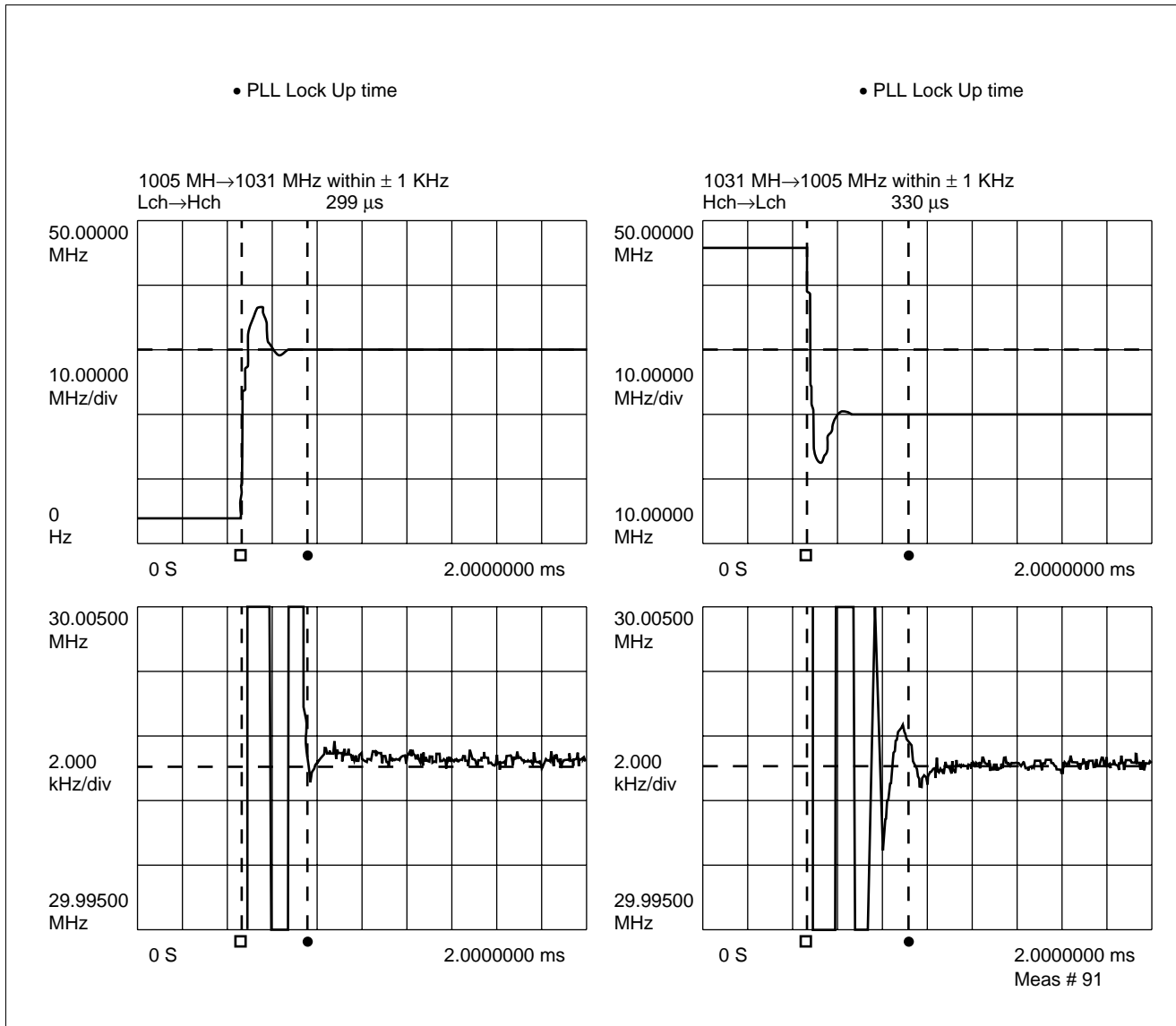
### • PLL Phase Noise



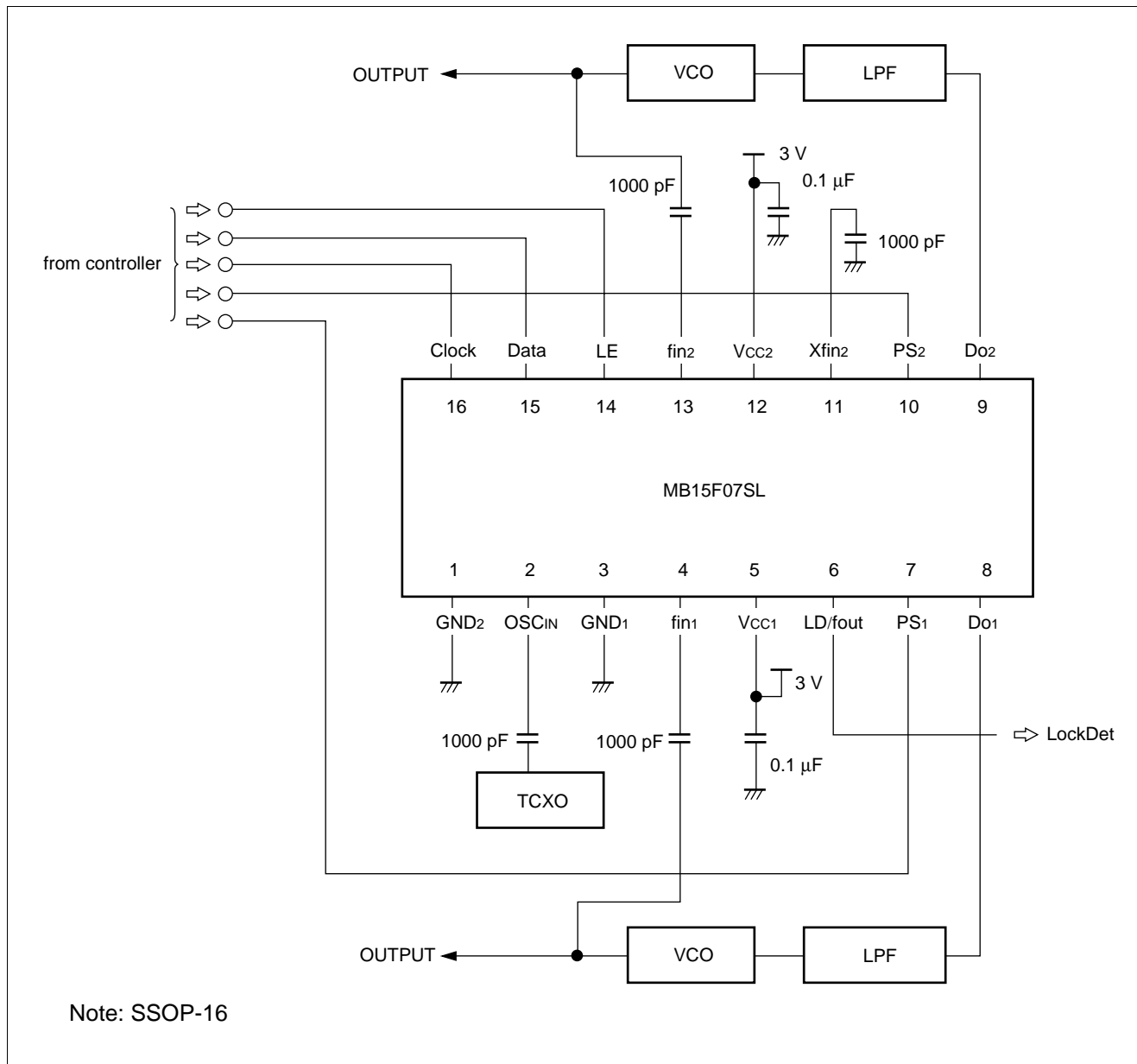
(Continued)

# MB15F07SL

(Continued)



## APPLICATION EXAMPLE



## USAGE PRECAUTIONS

- (1)  $V_{CC2}$  must equal  $V_{CC1}$ .  
Even if either PLL 2 or PLL 1 is not used, power must be supplied to both  $V_{CC2}$  and  $V_{CC1}$  to keep them equal. It is recommended that the non-use PLL is controlled by power saving function.
- (2) To protect against damage by electrostatic discharge, note the following handling precautions:
  - Store and transport devices in conductive containers.
  - Use properly grounded workstations, tools, and equipment.
  - Turn off power before inserting or removing this device into or from a socket.
  - Protect leads with conductive sheet, when transporting a board mounted device.

# MB15F07SL

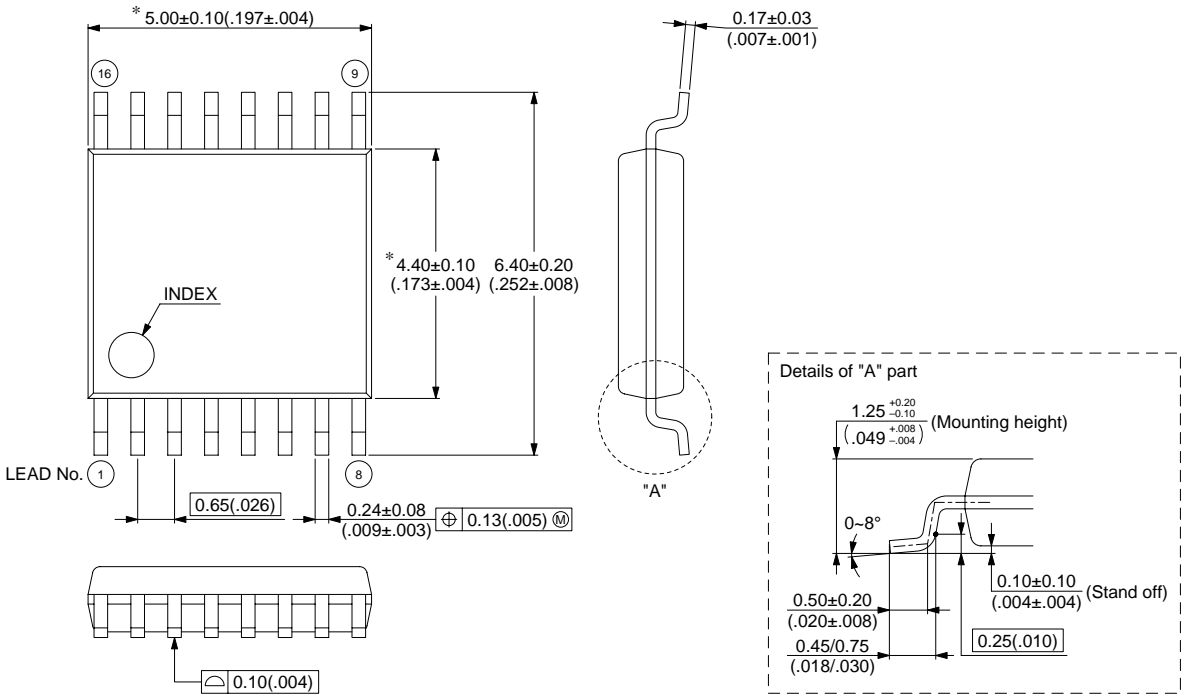
## ■ ORDERING INFORMATION

Part number	Package	Remarks
MB15F07SLPFV1	16-pin plastic SSOP (FPT-16P-M05)	
MB15F07SLPV1	16-pad plastic BCC (LCC-16P-M04)	

■ PACKAGE DIMENSIONS

16-pin plastic SSOP  
(FPT-16P-M05)

Note 1 ) \* : These dimensions do not include resin protrusion.  
Note 2 ) Pins width and pins thickness include plating thickness.



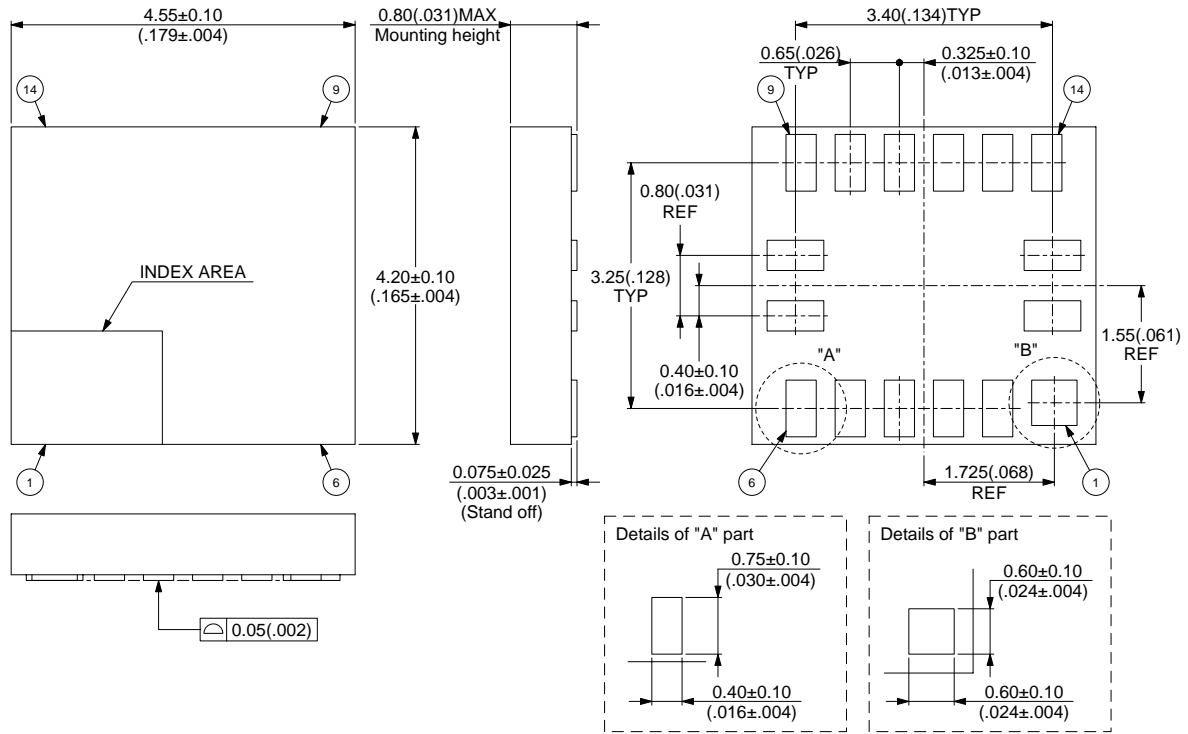
© 1999 FUJITSU LIMITED F16013S-3C-5

Dimensions in mm (inches)

(Continued)

# MB15F07SL

16-pad plastic BCC  
(LCC-16P-M04)



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Dimensions in mm (inches)

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